

Compact Behavioural Modelling of Electromagnetic Effects in On-Chip Interconnect

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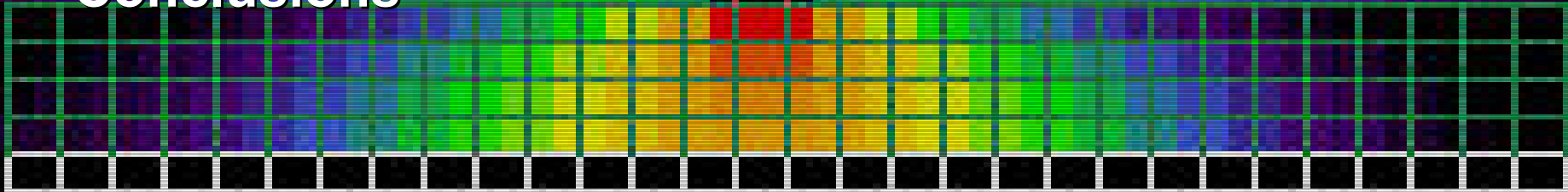
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Contents

- Introduction
- Modelling “flow”
- From Maxwell’s Equations to circuit simulation
 - Example 1: **one wire, load modelling**
 - Example 2: **two wires with cross-talk**
- Conclusions

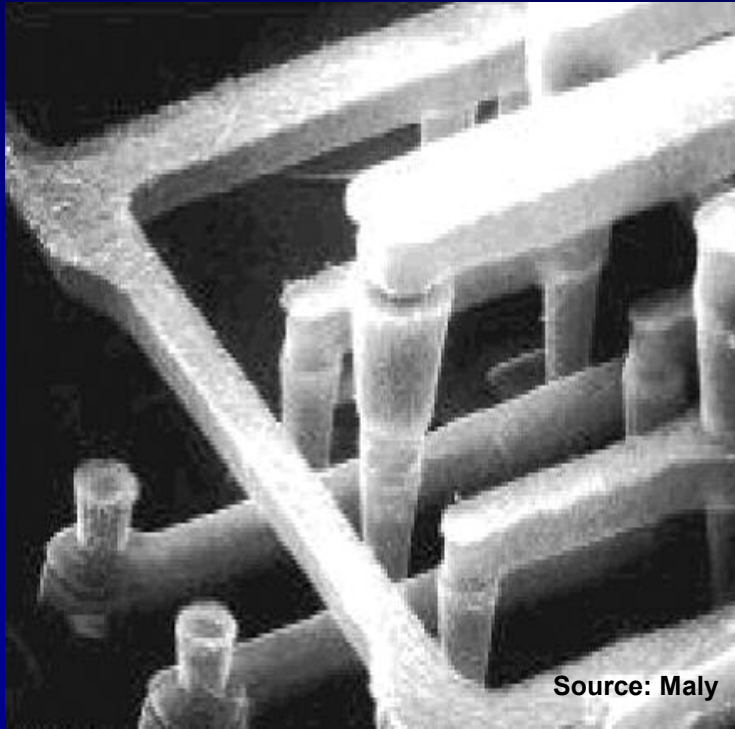


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Why?



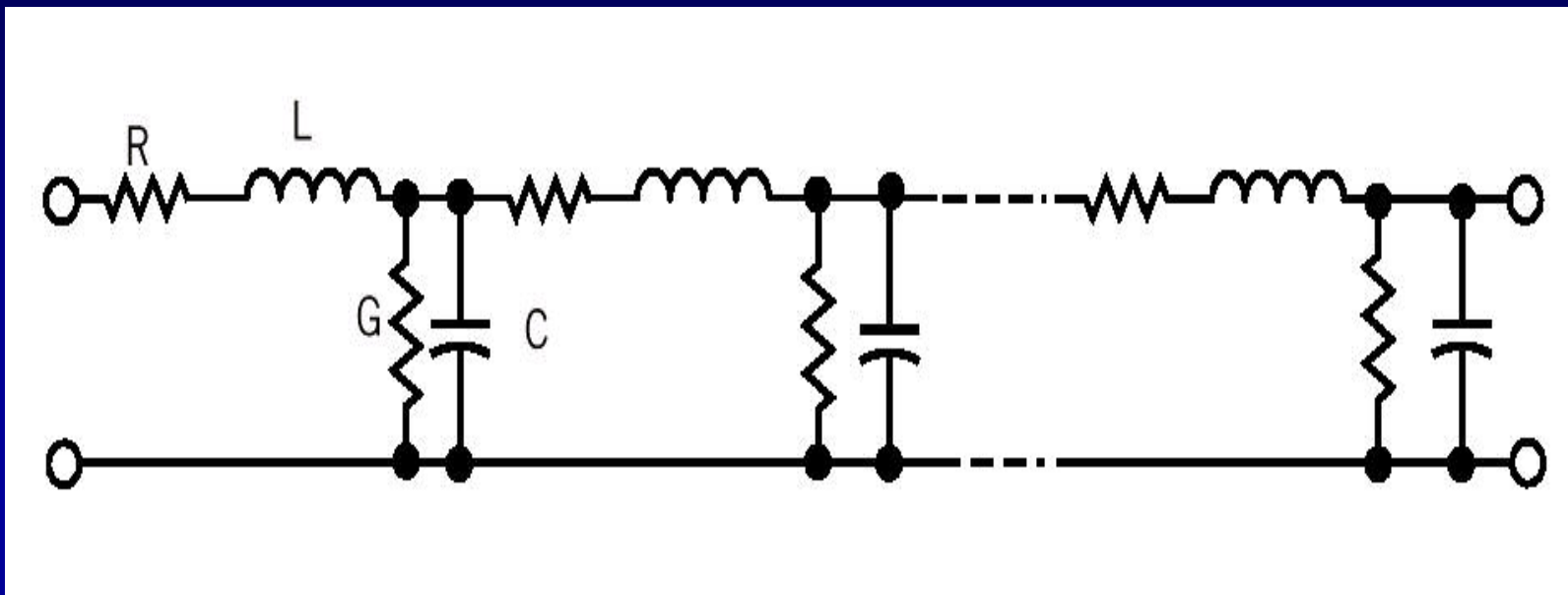
- Find limiting factors in high-speed digital circuits
- Reference for validation of future design rules
- Reference for validation of alternative models

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Other approaches



RLC lumped models
Transmission line models
ROM techniques

} Modelling assumptions?

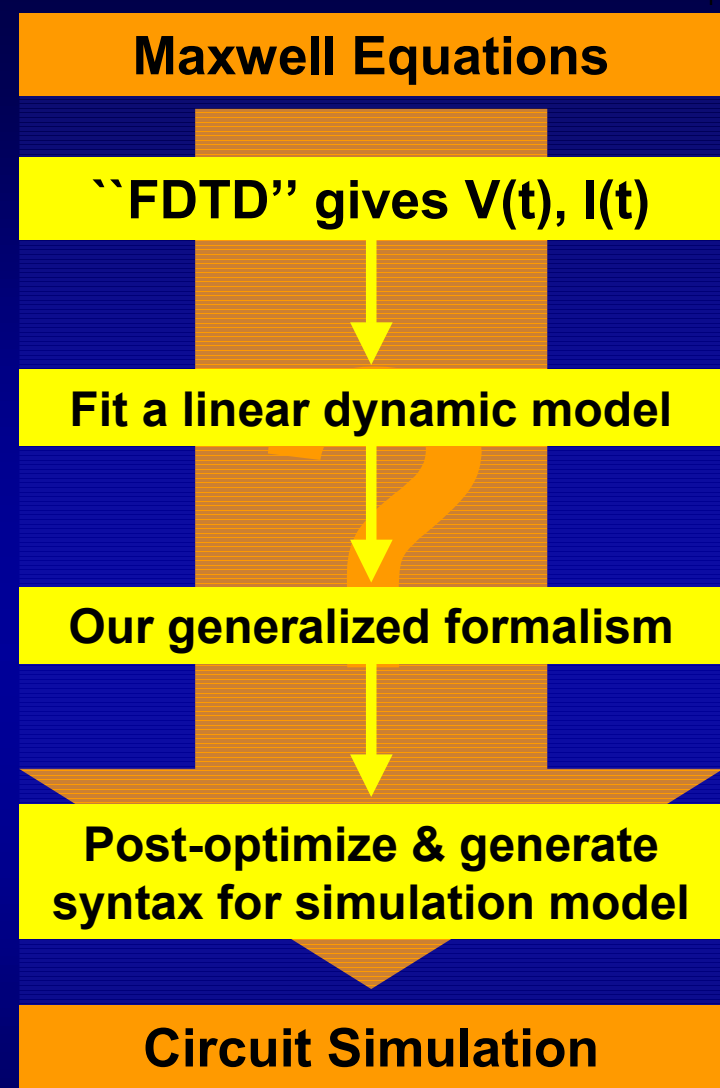
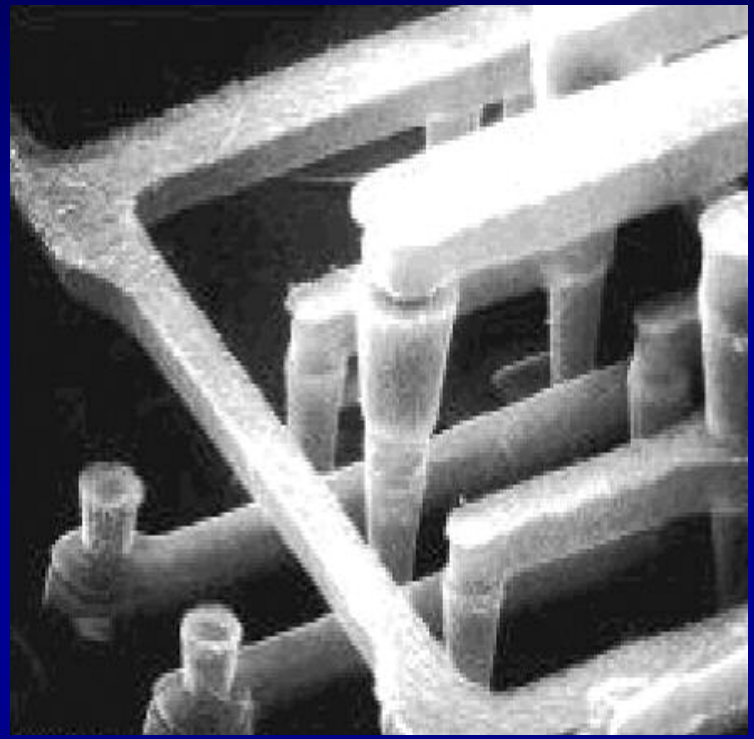
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Modelling flow?



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FDTD method

FDTD = **Finite Difference Time Domain**: a method for solving the Maxwell Equations

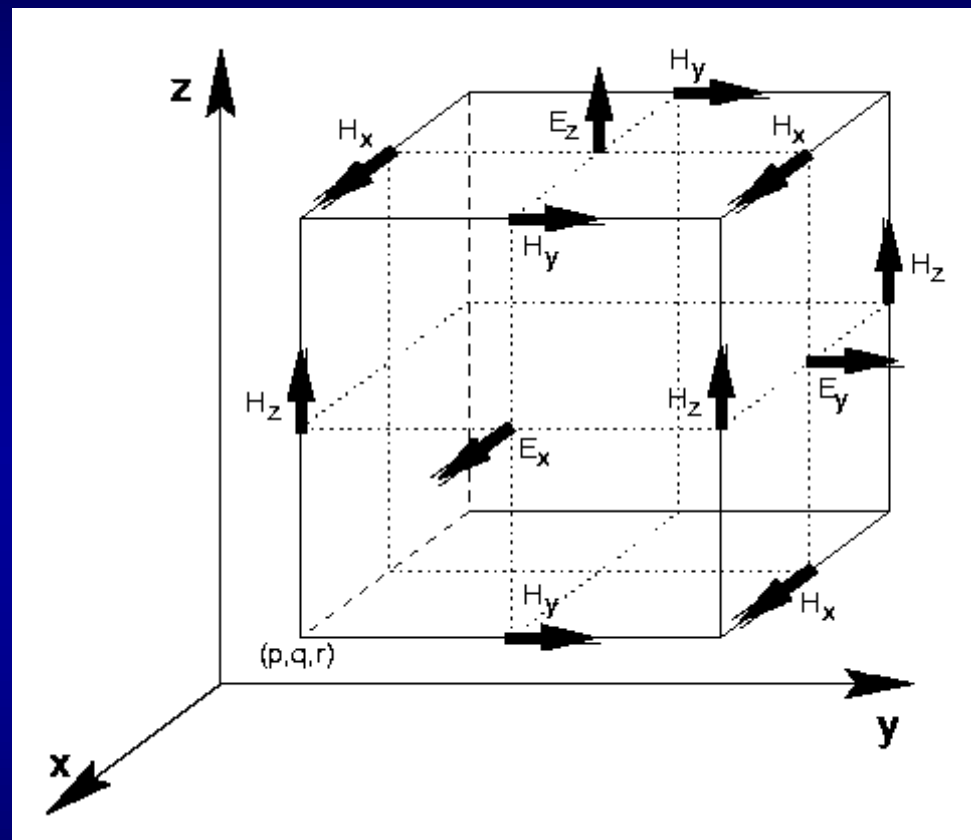
- Discretizes and solves Maxwell's Equations in both space and time

$$\nabla \cdot \vec{D} = \rho_f$$

$$\nabla \cdot \vec{B} = 0$$

$$\nabla \times \vec{E} = \frac{\partial \vec{B}}{\partial t}$$

$$\nabla \times \vec{H} = \frac{\partial \vec{D}}{\partial t} + \vec{J}_f$$



Also yields voltages and currents

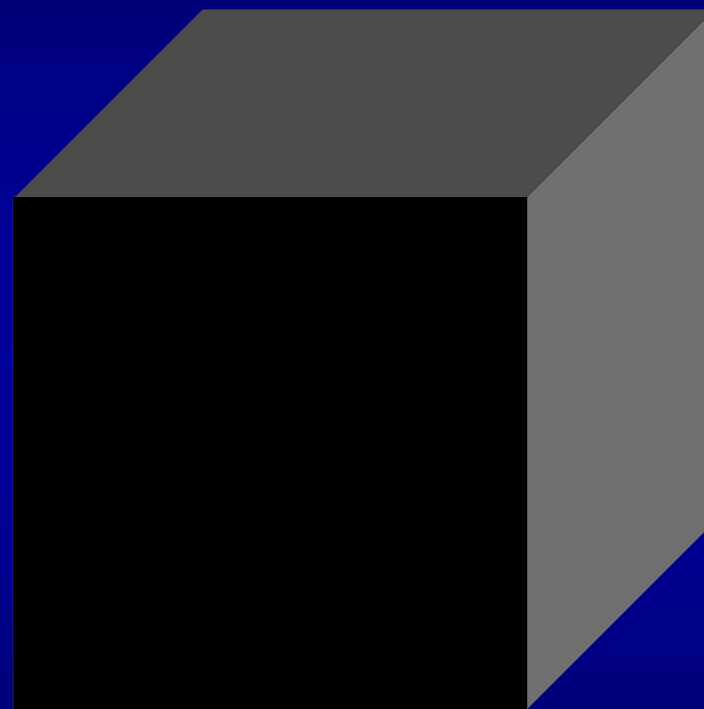
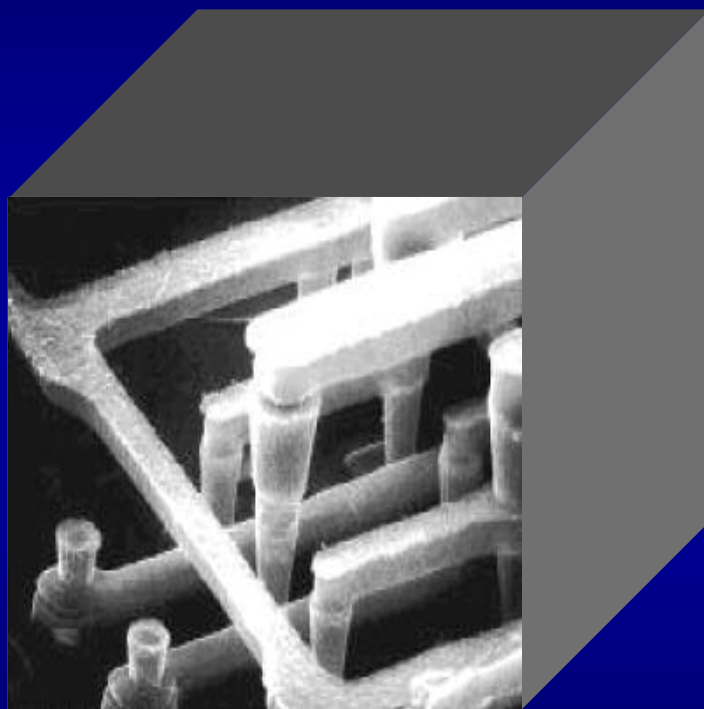
- CPU intensive!

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FDTD: CPU time = f(mesh)



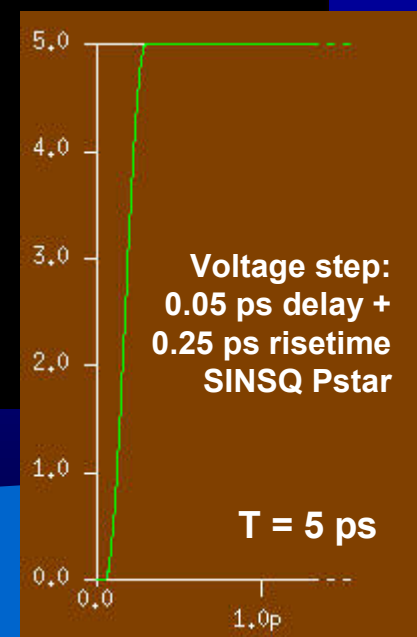
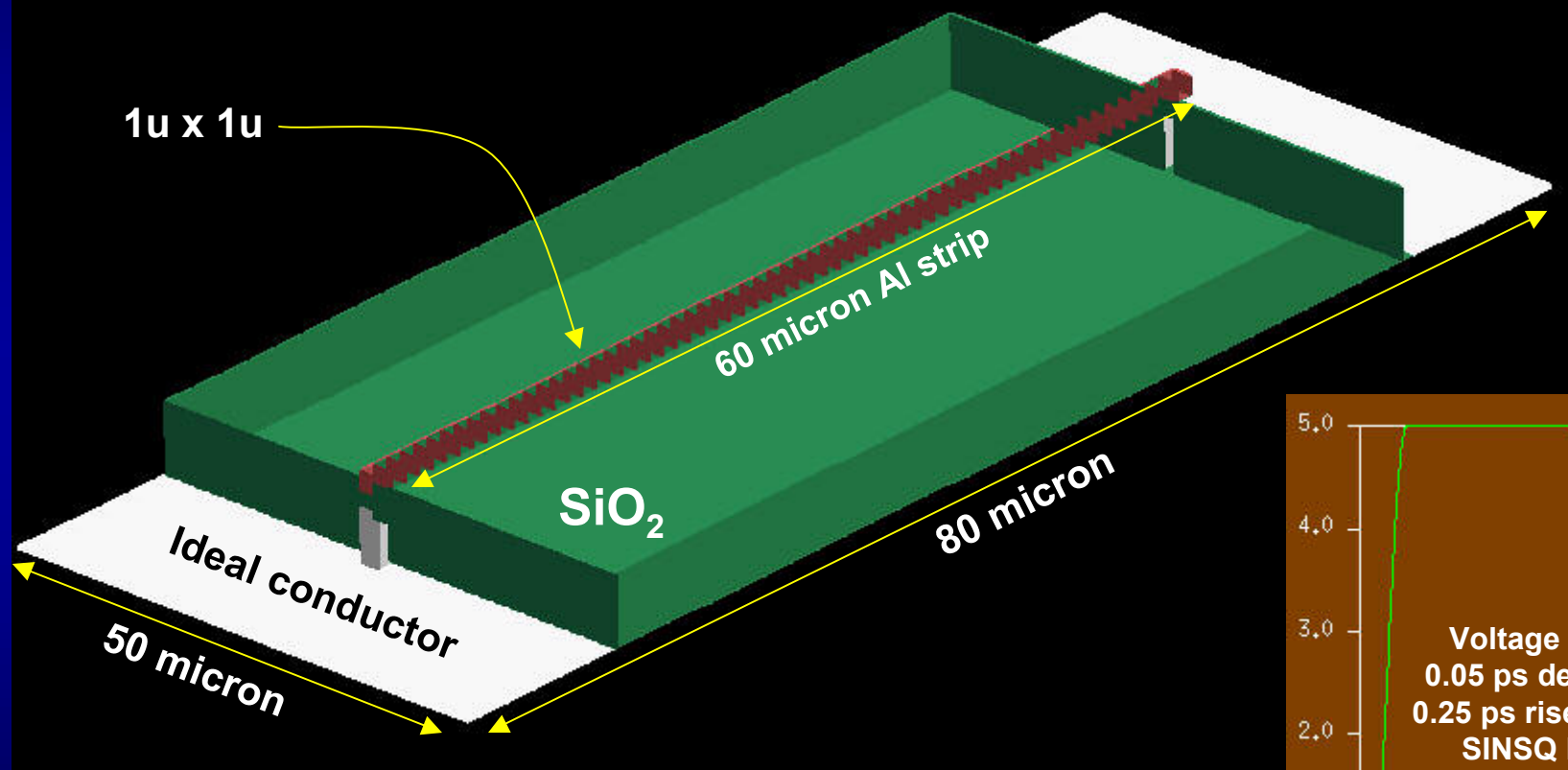
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Using FDTD

Mesh: 250,000 cells @ 2500 time points



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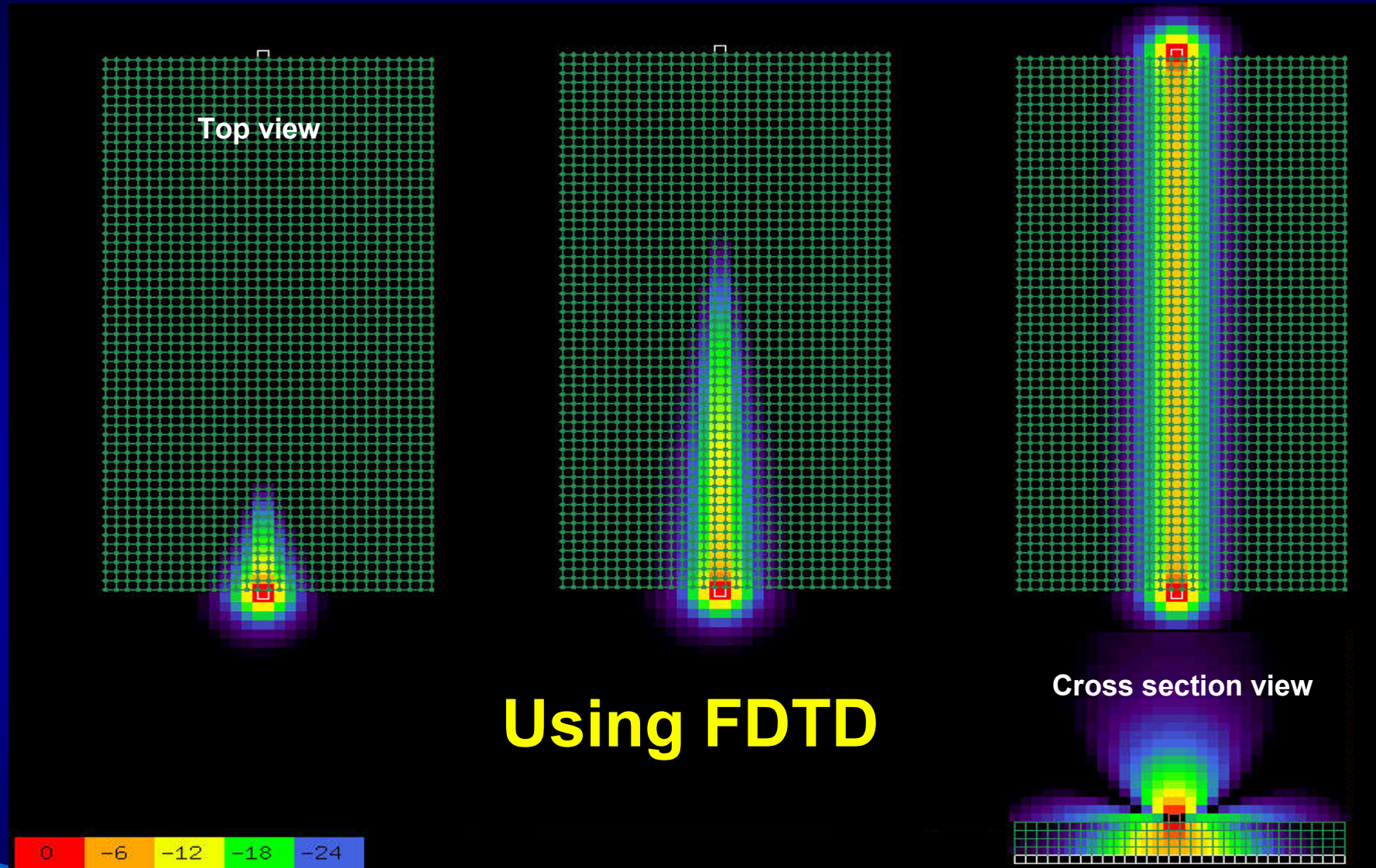


$t = 0.2$ picosecond

$t = 0.4$ picosecond

$t = 4.6$ picosecond

PBLM 9



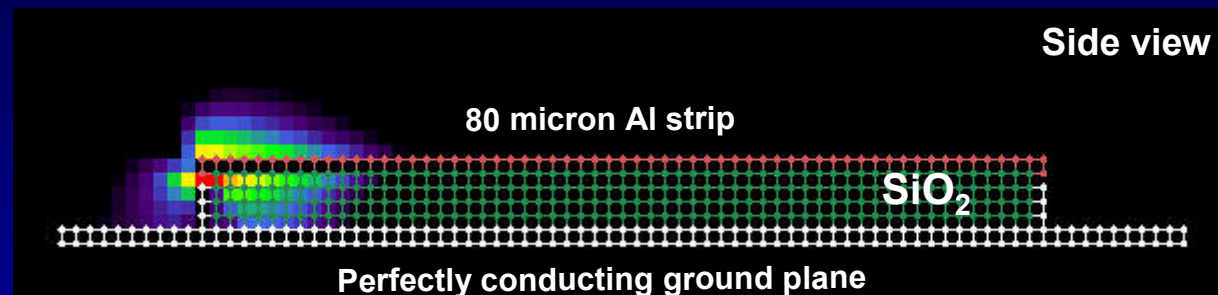
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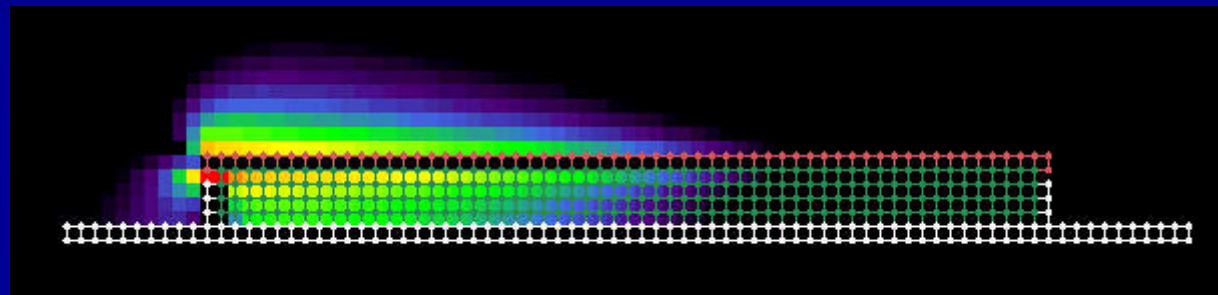
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Using FDTD

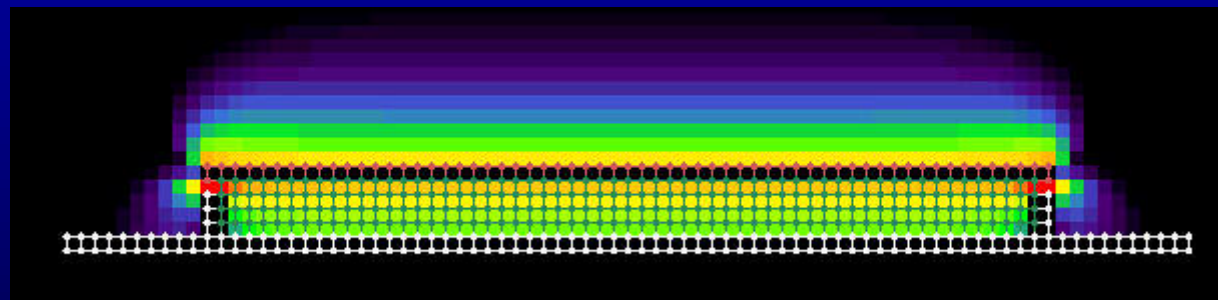
$t = 0.2$ picosecond



$t = 0.4$ picosecond



$t = 4.6$ picosecond



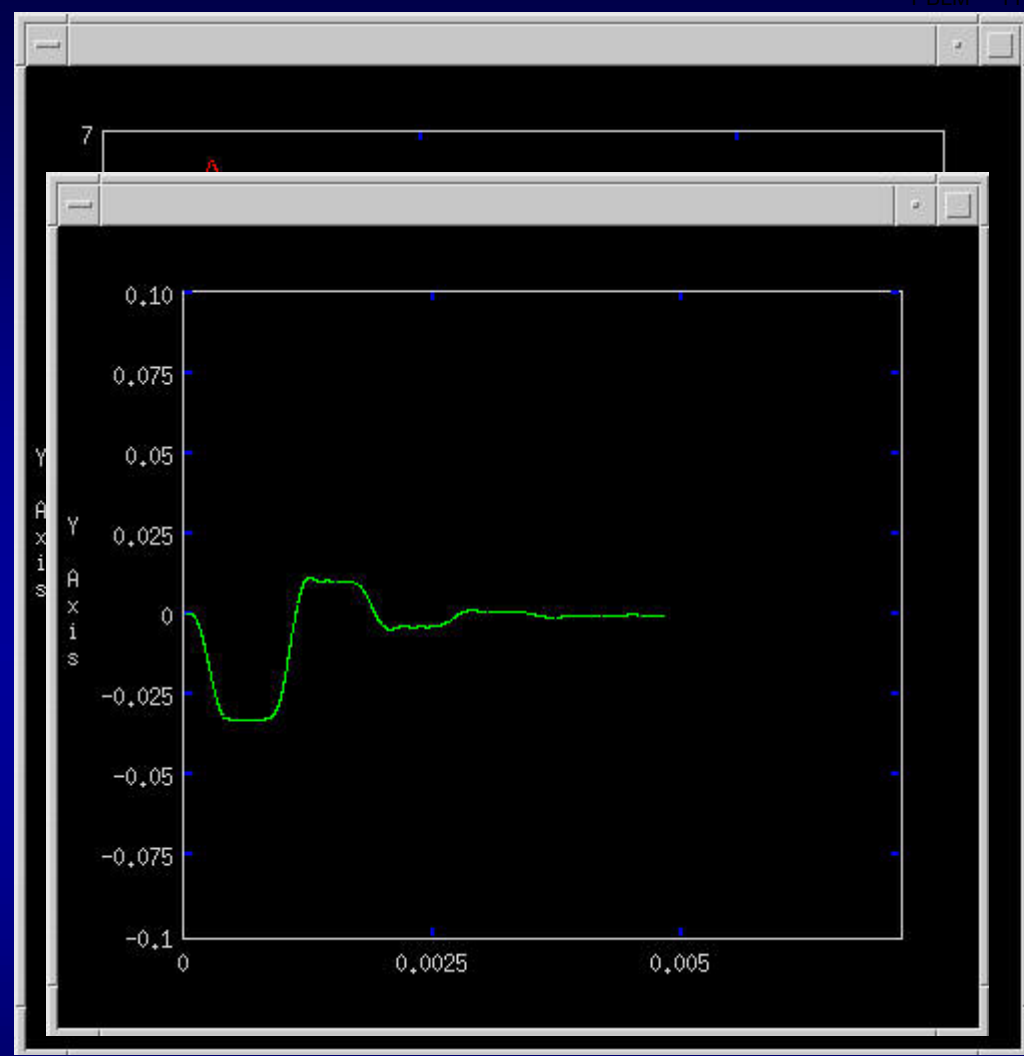
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Using FDTD

- 500 GHz reflections
 - Reflections give overshoot and affect wave shape at source side
 - Analyze beyond measurement options
 - Results sanity check:
 ~0.4 ps for 60 micron:
 $1.5 \times 10^8 \text{ m/s} \approx c / \sqrt{3.9}$,
 (3.9 is rel. perm. SiO₂)

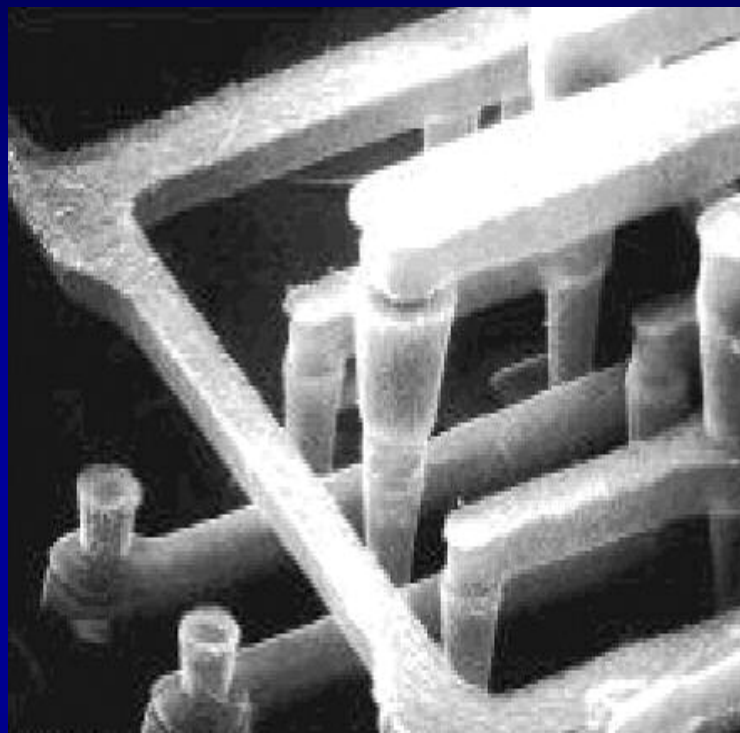


Current density at source side

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Maxwell Equations

FDTD gives $V(t)$, $I(t)$

Circuit Simulation

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Linear State Space Modelling

- **Assume** linear state space model:

Matrix equations

$$\begin{aligned} \mathbf{x}'(t) &= \mathbf{A} \mathbf{x}(t) + \mathbf{B} \mathbf{u}(t) \\ \mathbf{y}(t) &= \mathbf{C} \mathbf{x}(t) + \mathbf{D} \mathbf{u}(t) \end{aligned}$$

- **Determine** parameter matrices **A, B, C, D** for given input vectors $\mathbf{u}(t)$ and output vectors $\mathbf{y}(t)$ such that a best fit is obtained
- **MOESP/4SID class of subspace identification algorithms**

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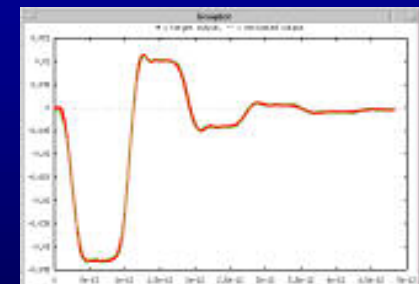
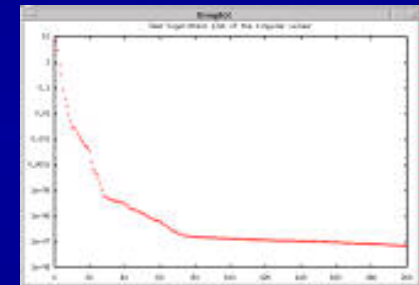
Linear State Space Modelling (MOESP/4SID)

Behavioural modelling based on time domain data (waveforms)

DeWilde, Verhaegen, Ciggaar, Meijer, Schilders

Steps:

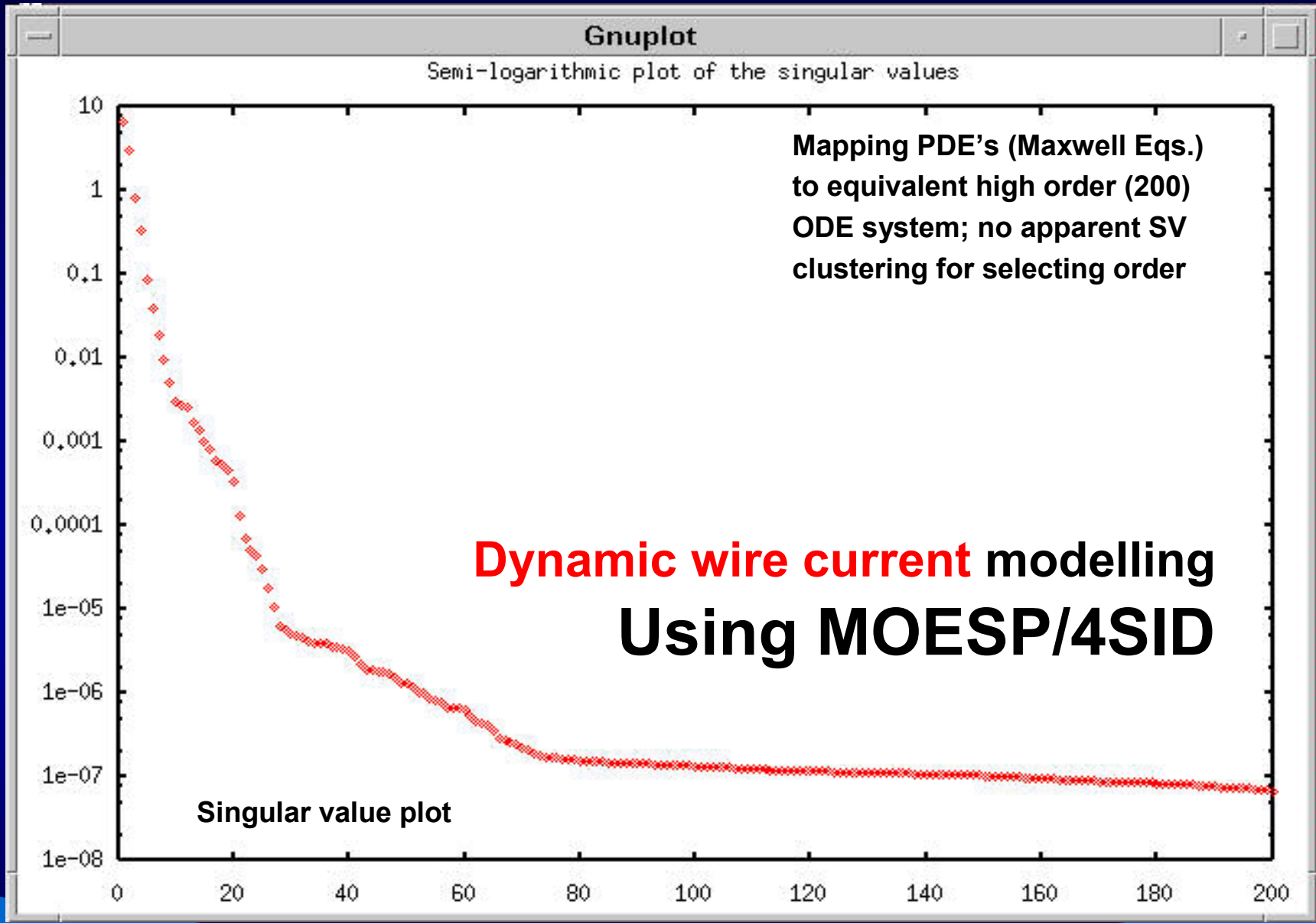
- **Initial order** sufficiently high, e.g., **200**
SVD plot to estimate # time constants
- **Reduce order** to desired value, e.g., **10**



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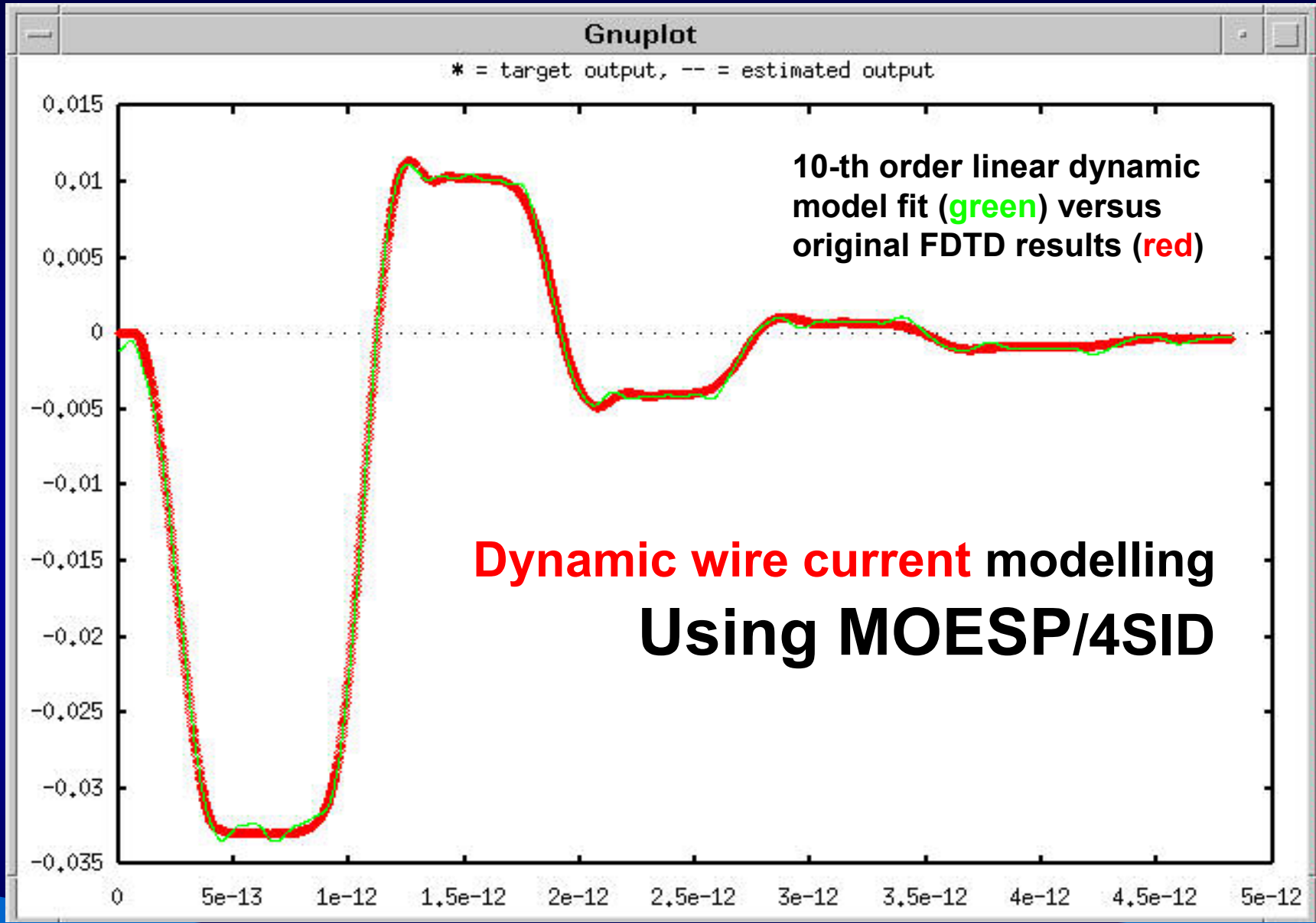
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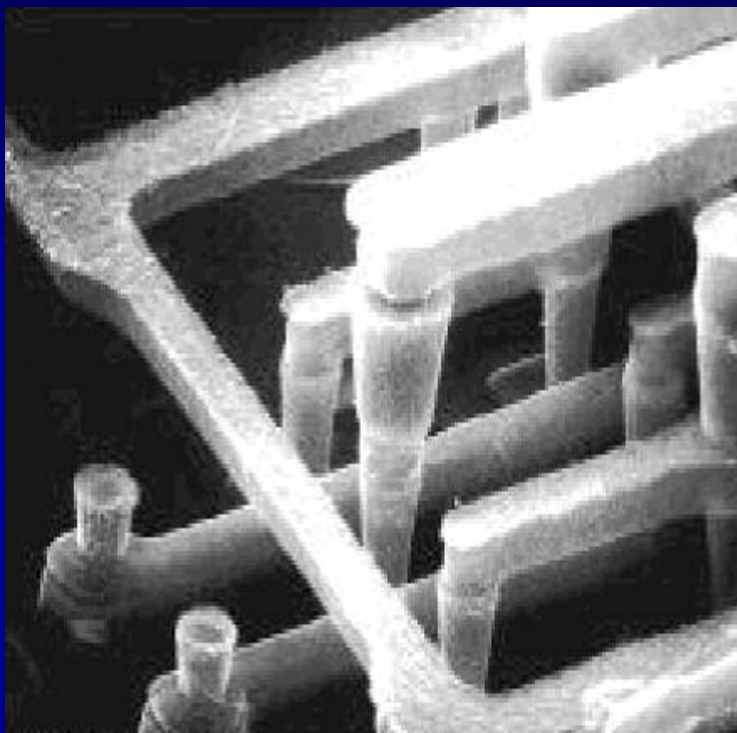
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Maxwell Equations

FDTD gives $V(t)$, $I(t)$



**Linear state space modelling
to get linear dynamic model**

Circuit Simulation

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Generalized Modelling Formalism

- **Map** linear state space model + parameters to our neural network modelling formalism

Constructive and mathematically exact!

- **Post-optimize** to deal with numerical artefacts of MOESP/4SID (instability & no implicit DC)
- Automatically **generate** lumped linear circuit models for Pstar, Spectre, VHDL-AMS, ...

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Basic multilayer perceptron theory + extensions (Meijer 1996)

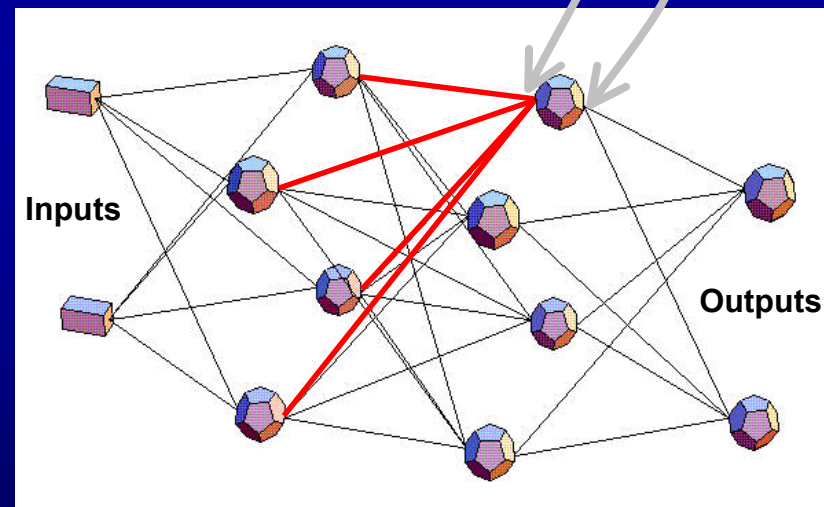
$$s_{ik} \triangleq \mathbf{w}_{ik} \cdot \mathbf{y}_{k-1} - \theta_{ik} + v_{ik} \cdot \frac{dy_{k-1}}{dt}$$

$$= \sum_{j=1}^{N_{k-1}} w_{ijk} y_{j,k-1} - \theta_{ik} + \sum_{j=1}^{N_{k-1}} v_{ijk} \frac{dy_{j,k-1}}{dt}$$

Weighted sum s_{ik}

$$\tau_{2,ik} \frac{d^2 y_{ik}}{dt^2} + \tau_{1,ik} \frac{dy_{ik}}{dt} + y_{ik} = \mathcal{F}^{(ik)}(s_{ik}, \delta_{ik})$$

Differential equation for neuron output y_{ik}



Feedforward neural network

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Neural Networks for Device and Circuit Modelling

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http://server506.hypermart.net/meijerpb/thesis/thesis_meijer.zip (11.5 MB)

Learning (=Optimization)

- Define cost function, e.g., $\sum (\text{model} - \text{data})^2$
 - Discretize and apply optimization algorithm*, involving combinations of
 - DC, TR and AC small signal analysis
 - DC, TR and AC sensitivity (for gradients)
- *Conjugate gradient, BFGS, ...**
- Risks: slow convergence, local minima

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Applying Generalized Formalism

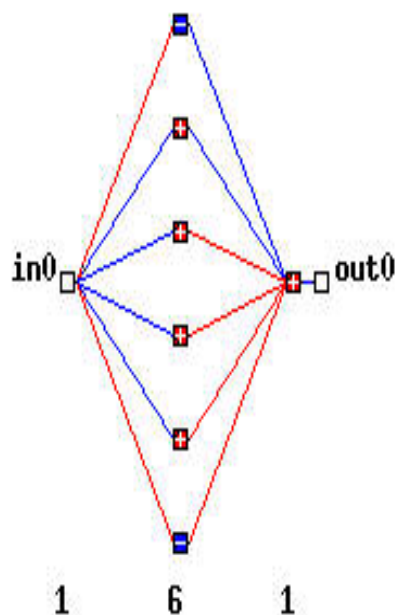
Post-optimize



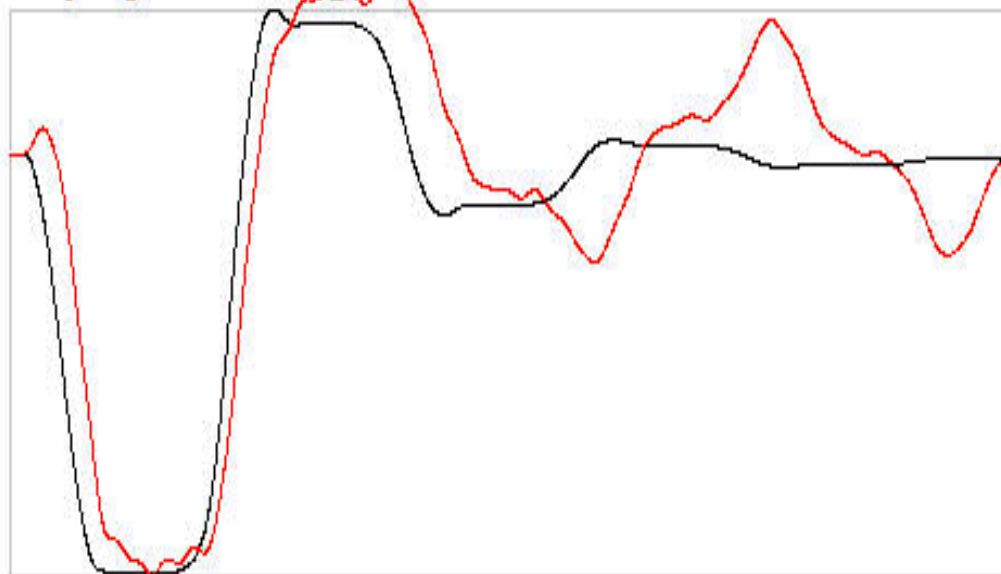
Fix MOESP/4SID artefacts:
ensure stable model &
fit with DC initial state



Network NET0:
7 neurons, 54 parameters



Replay

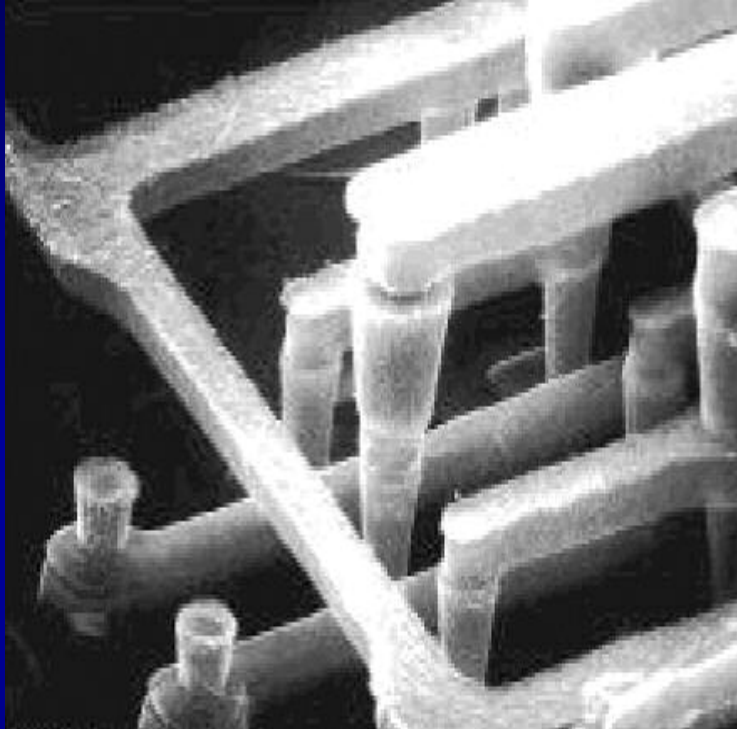


TR: targets solid, black

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Maxwell Equations

FDTD gives $V(t)$, $I(t)$

**Linear state space modelling
to get linear dynamic model**

Our generalized formalism

**Post-optimize & generate
syntax for simulation model
(lumped linear circuit model)**

Circuit Simulation

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Sep 27, 2000
13:33:57

Pstar analog test bench generated by NEUREKA 1.24++

FDTD results and Neureka/Pstar NN model results

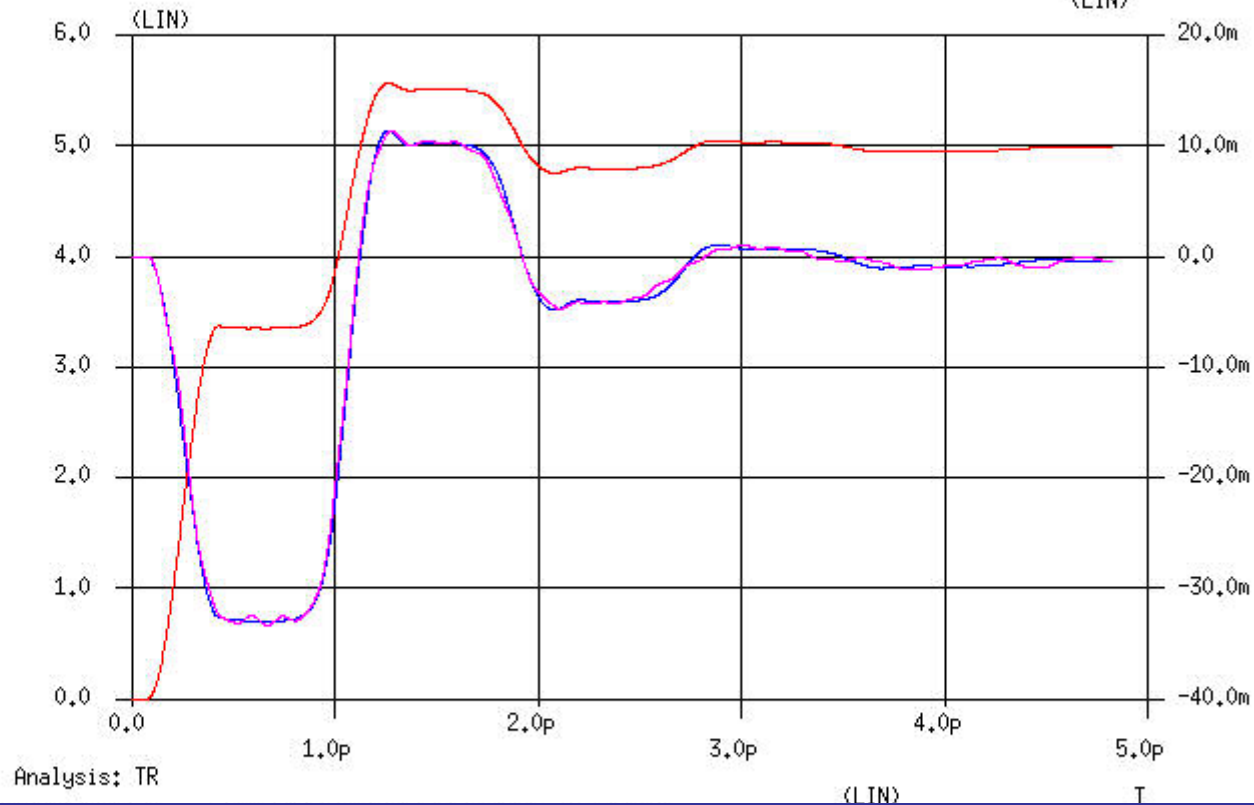
- y1-axis -

VIN1

- y2-axis -

TARGET0

I(WIRES0_1\T0)



Circuit simulation results vs FDTD

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Verify model generalization

- **Linear model:** modelling for one signal with all (relevant) frequencies should suffice - **in theory!**
- **Verify:** define a **different stimulus** and check if the FDTD simulation still matches results for the **unchanged** circuit model simulation

If so, that will confirm that the circuit model indeed applies to **all stimuli** - and not just the one(s) used during modelling

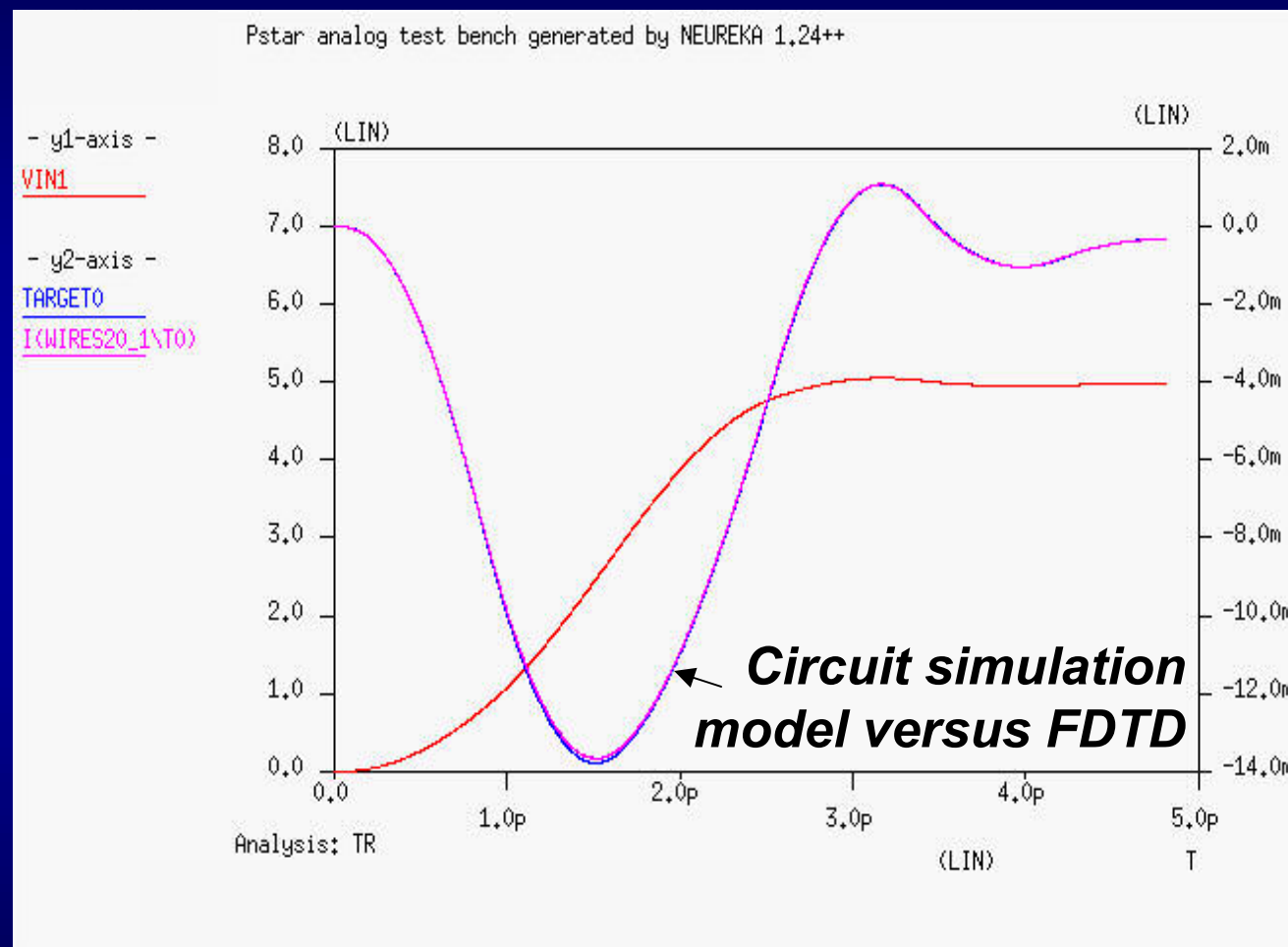
Verify model generalization [1]

- **New stimulus STEP with slope $\neq 10$, applied to**

- FDTD simulation

- **Unchanged** circuit simulation model

Excellent fit!



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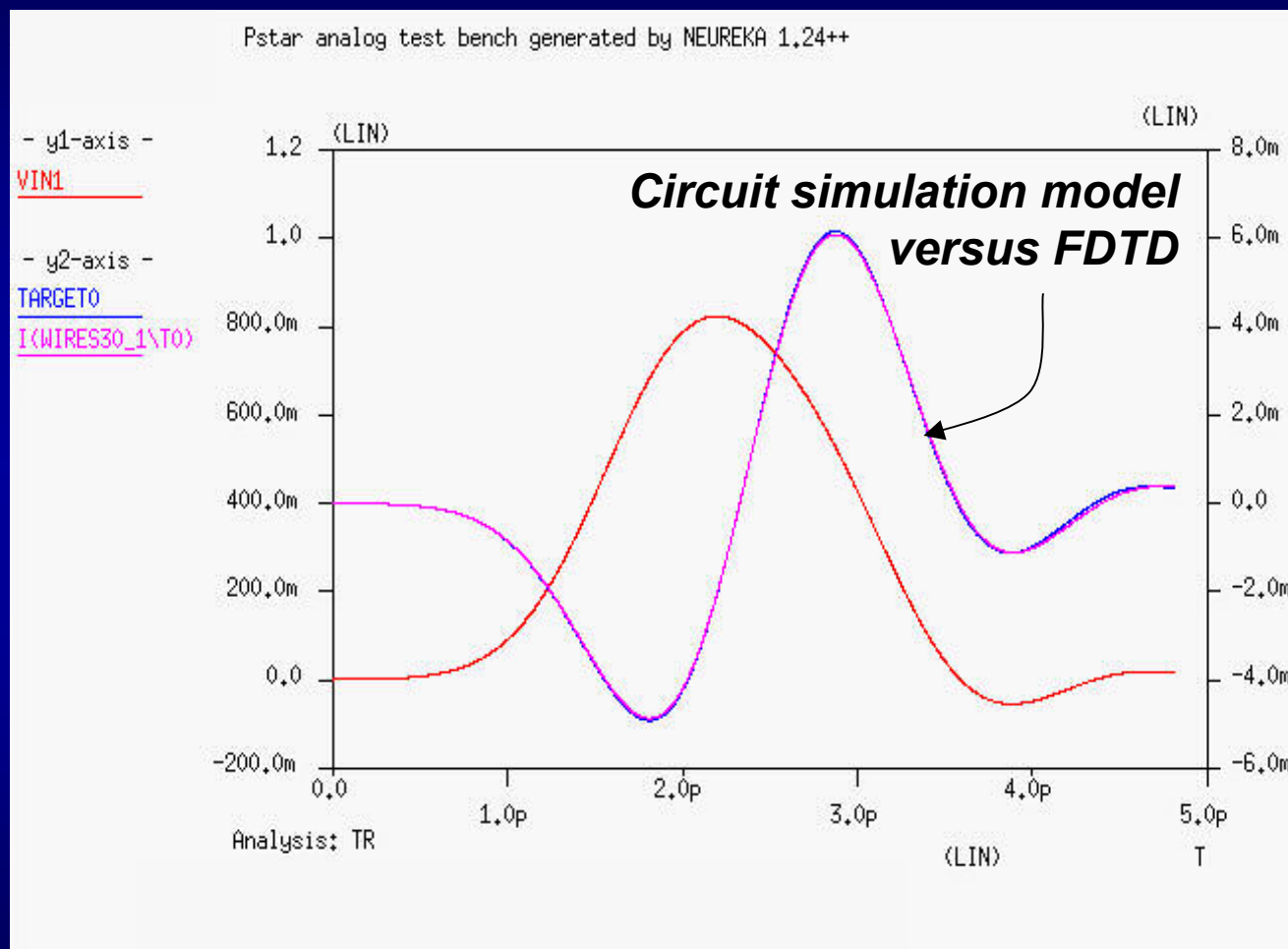
Verify model generalization [2]

- **New stimulus GAUSSIAN** applied to

- FDTD simulation

- **Unchanged** circuit simulation model

Excellent fit!



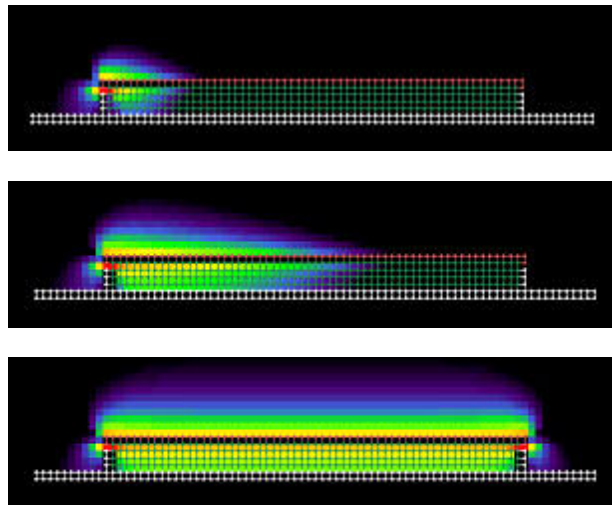
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Single Wire Modelling

FDTD simulation of
Maxwell Equations
in space and time

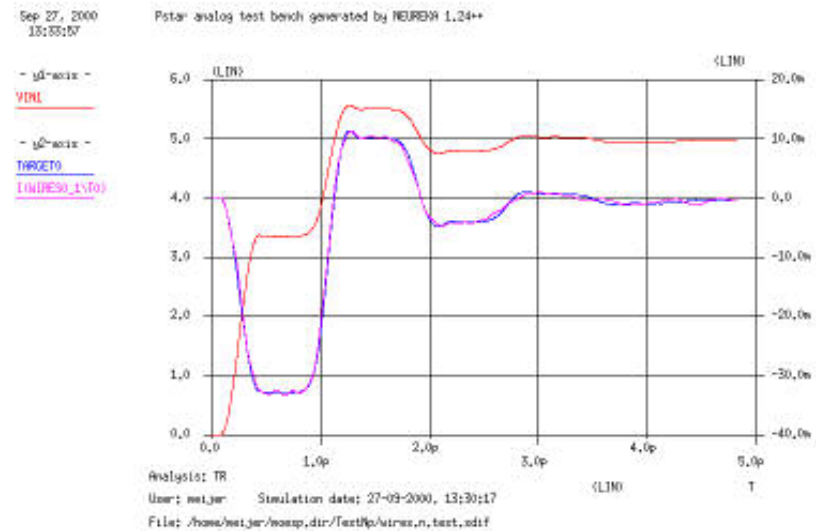


Model Eqs. $10^5 - 10^6$



Complex
wire load
modelling

Lumped linear dynamic
circuit simulation model

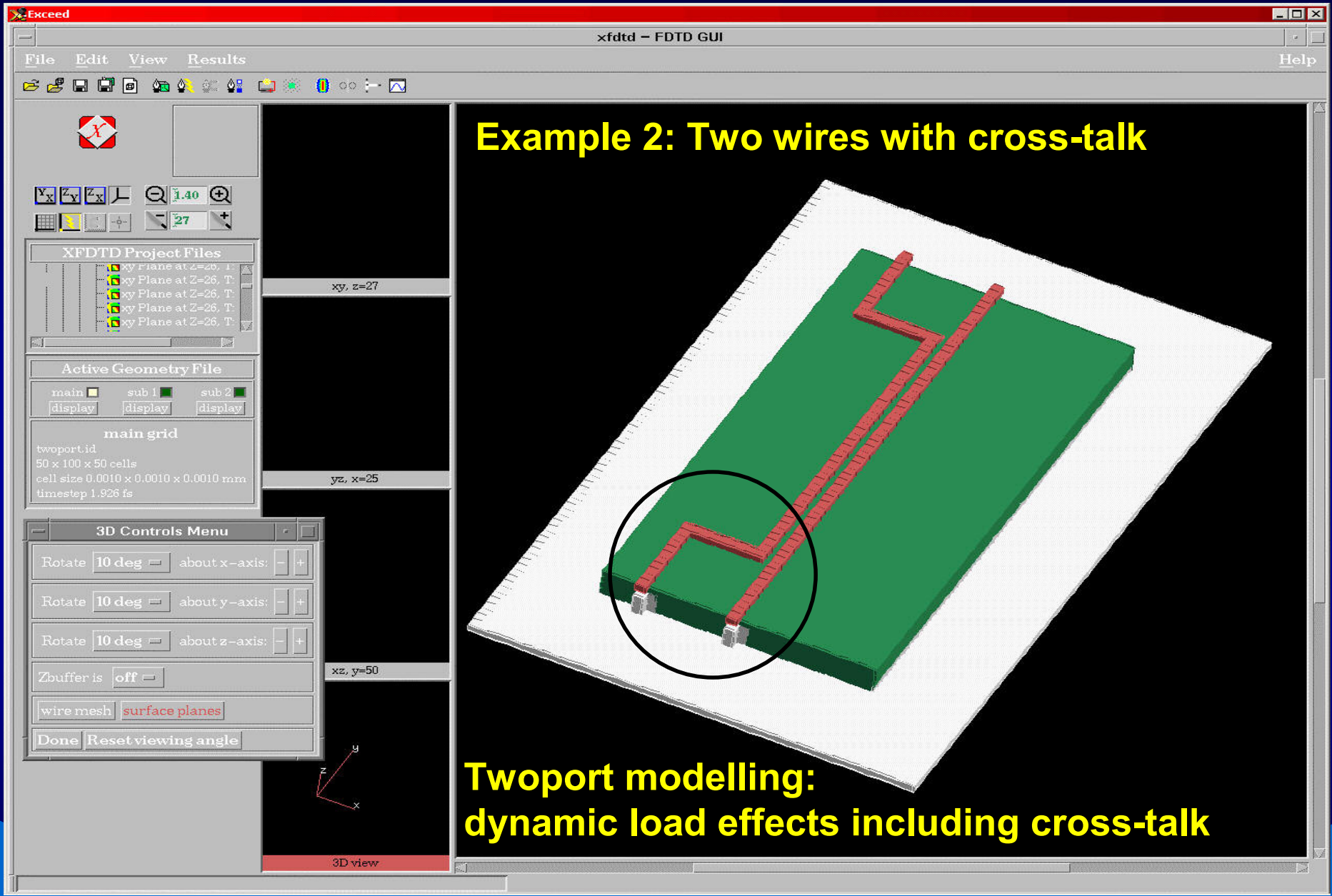


Orders of magnitude gain in simulation speed
while preserving detailed (parasitic) effects

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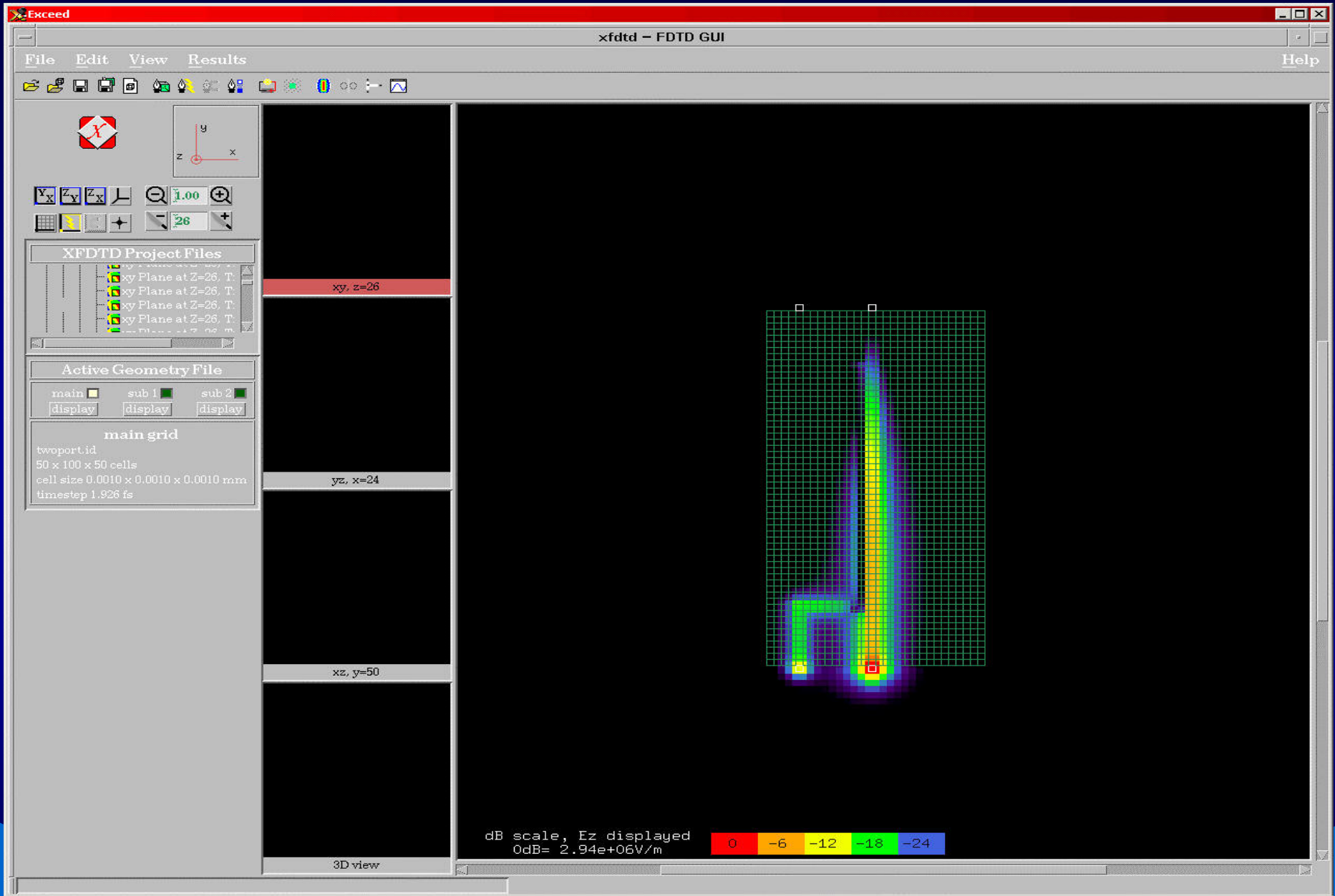
Example 2: Two wires with cross-talk

Twoport modelling:
dynamic load effects including cross-talk

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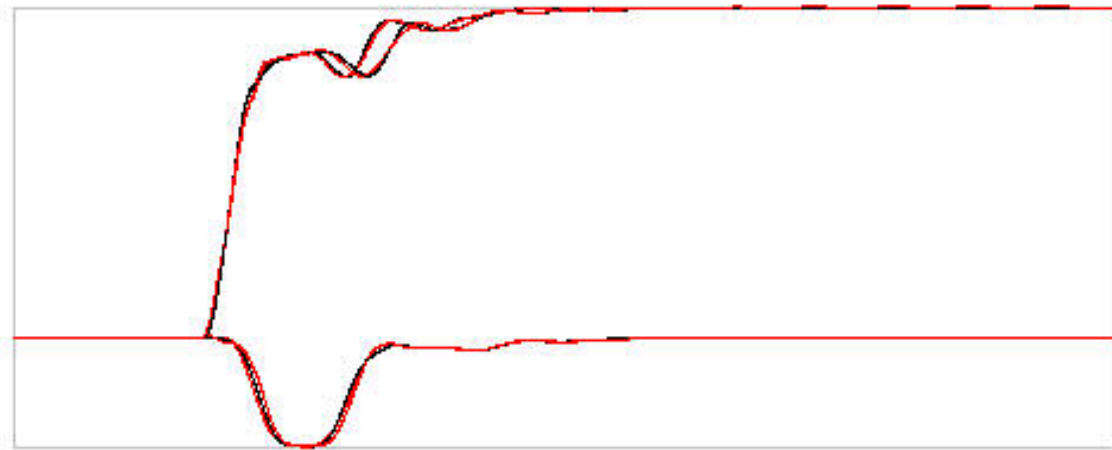
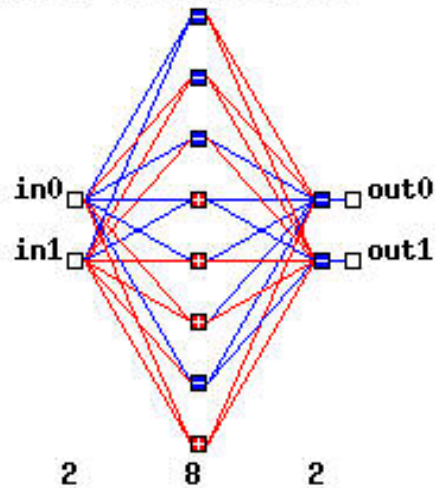


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Network NET0:
10 neurons, 108 parameters

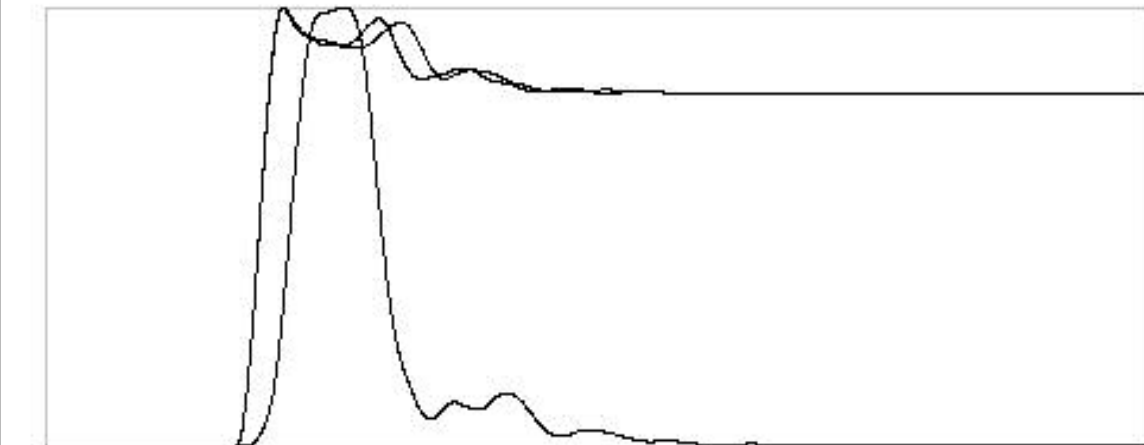


Max
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Func

NEUREKA:
Neural Network Circuit Modeling
Software for Analog Behavioral
(Macro-)Modeling of Nonlinear
Dynamic Sub-Circuits & Devices

(c) P.B.L. Meijer 1991 - 2001
Digital Design & Test
Philips Research Laboratories
Eindhoven, The Netherlands.

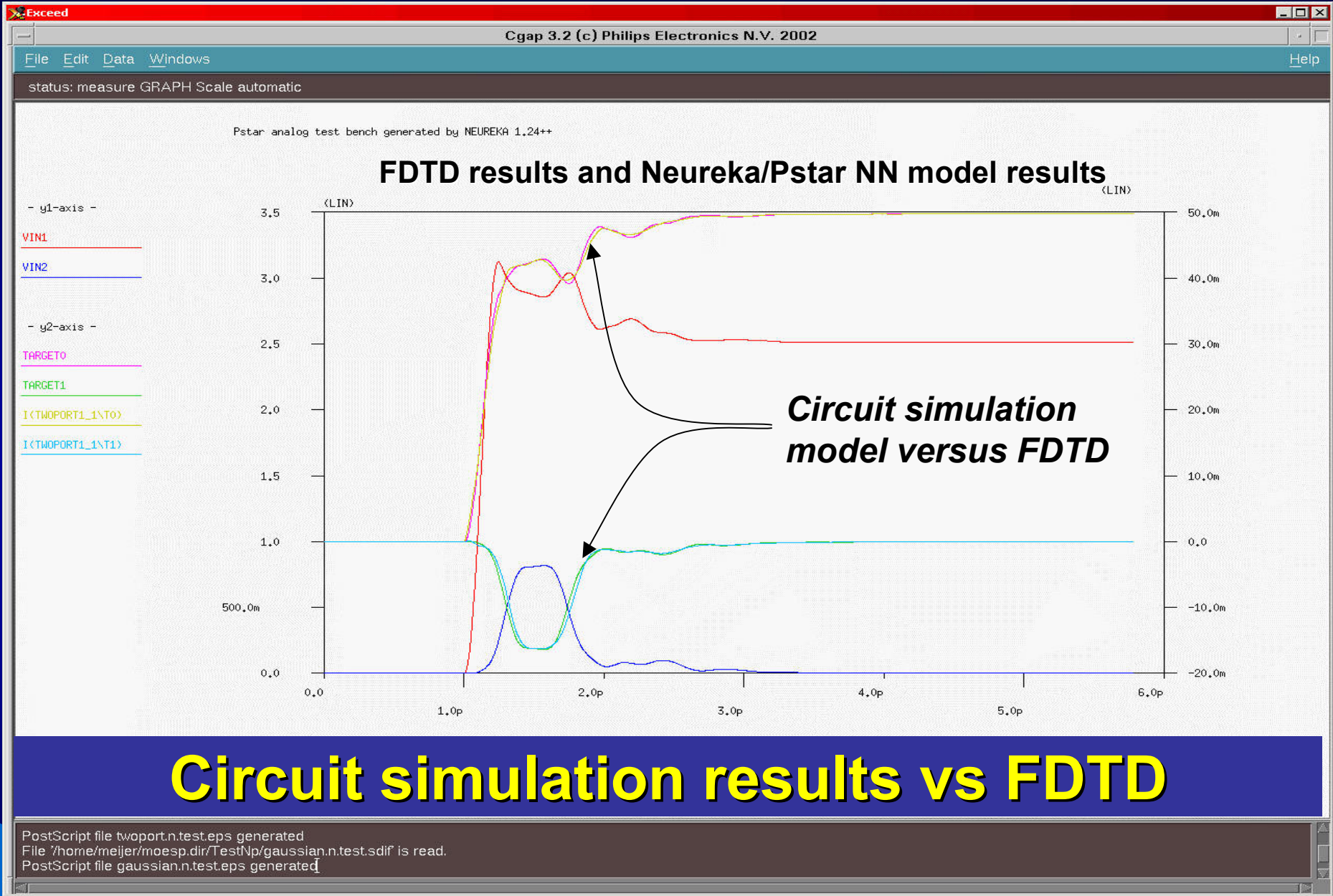
*** VERSION 1.24++ ***



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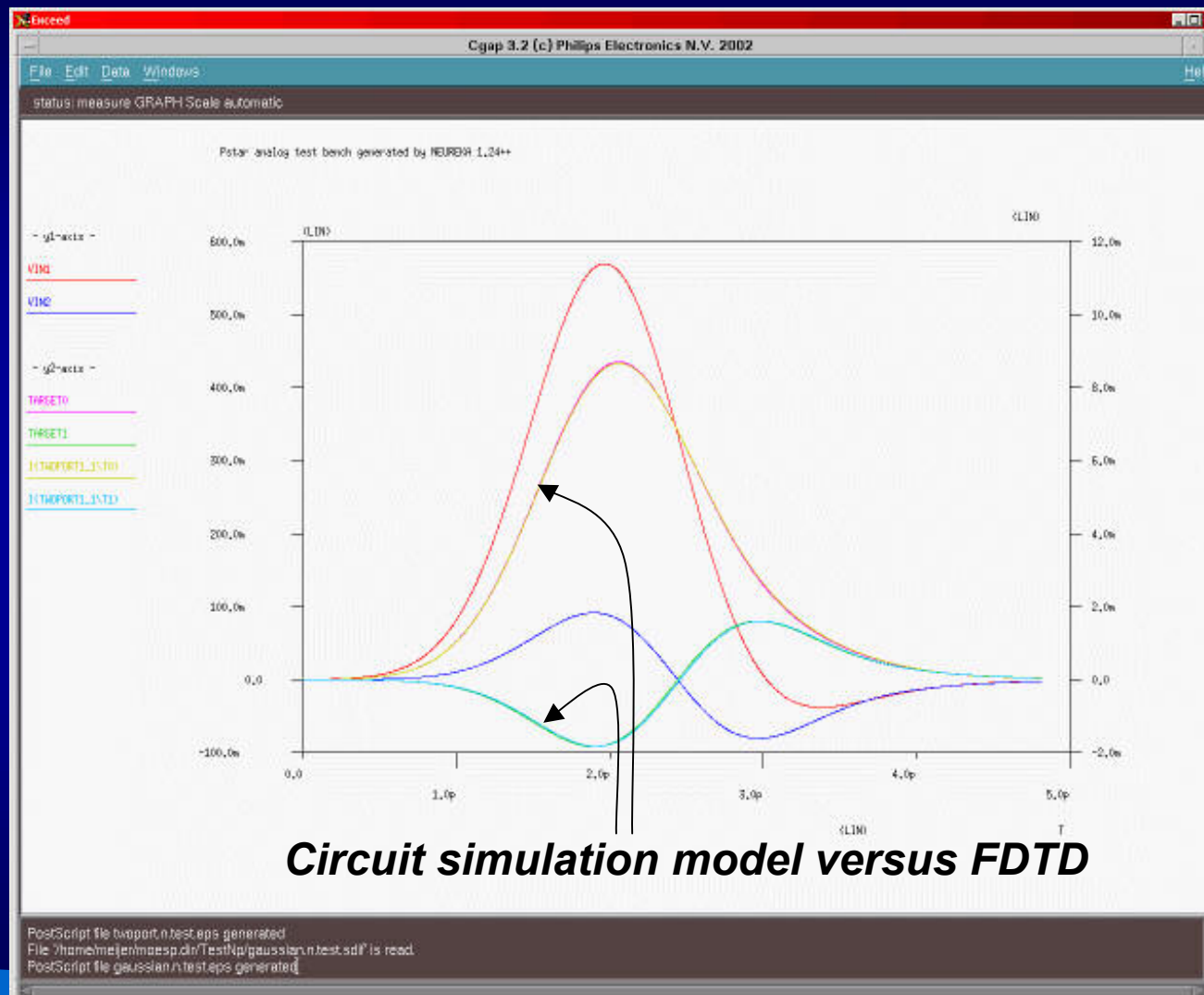
Verify twoport model generalization

- **New stimulus GAUSSIAN applied to**

- FDTD simulation

- **Unchanged** circuit simulation model

Excellent fit!



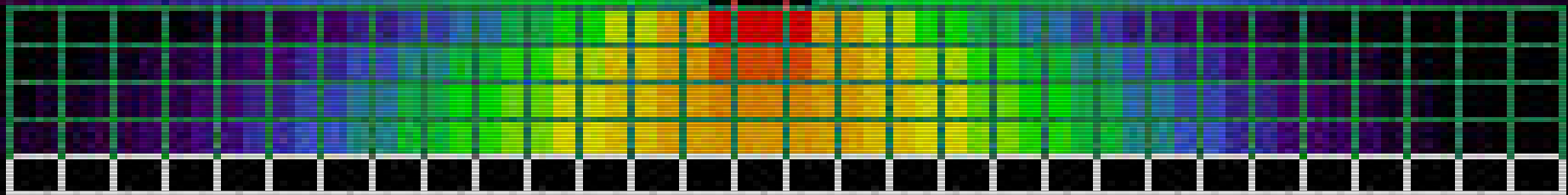
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Conclusions

- New numerical **interconnect analysis** options going well **beyond 100 GHz**
- Many/All RF4D parasitics can be included: **capacitive** and **inductive** effects, **skin** effect
- Reference for validation of new design rules
- Reference for validation of alternative models



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